

CAN Bus 2.0A/2.0B General and SAE J1939

Supported series: CAN Bus 2.0A / CAN Bus 2.0B / SAE J1939.

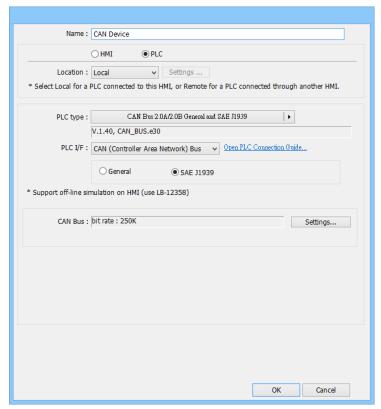
HMI Setting:

Parameters	Recommended	Options	Notes
DI C turno	CAN Bus 2.0A/2.0B General and SAE J1939		
PLC type	General	General / SAE J1939	
Baud rate	250K	20K~1M	
Reset RDO when			

Online simulator	NO	Extend address mode	NO
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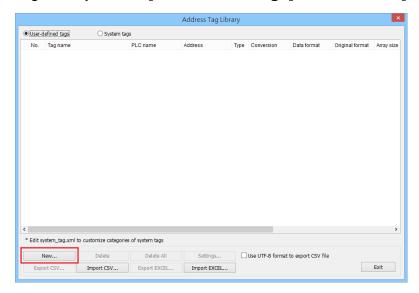
How to import SAE J1939 address tags:

1. In EasyBuilder Pro add [CAN Bus 2.0A/2.0B General and SAE J1939] driver.





2. Open Address Tag Library, select [User-defined tags] and then click [New].



3. Name: Enter the tag name.

PLC: Select the SAE J1939

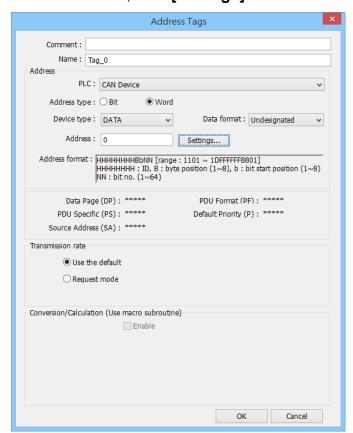
Address type: Select Bit or Word.

Transmission rate:

If [Use the default] is selected, then HMI will wait for the reply from CAN device.

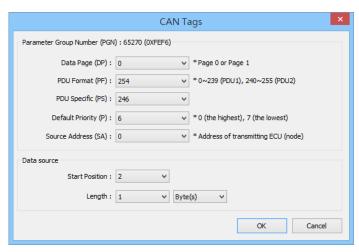
If [Request mode] is selected, then HMI will send polling packet.

After entering the above information, click [Settings].

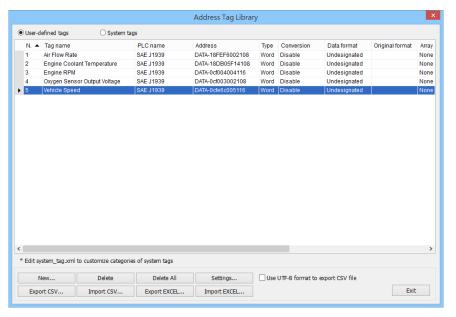




Please set the following parameters according to the specification of the CAN device used.



5. After building the tags click [Exit].





Device Address:

Bit/Wor	Device type	Format	Memo
	DATA_Bit	НННННННВЬ	H: ID
В			B: Byte position (1~8)
			b: Bit start position (1~8)
В	RTR	НННННННВb	H: ID
			B: Byte position (1~8)
			b: Bit start position (1~8)
W	DATA	НННННННВЫМ	H: ID
			B: Byte position (1~8)
			b: Bit start position (1~8)
			NN: Bit no. (1~64)

Wiring Diagram:

CANBus

The serial port pin assignments may vary between HMI models, please click the following link for more information.



To minimize signal reflection on the CAN bus network, termination resistors should be installed at both ends of the network, as shown in the following figure.

