

Panasonic MINAS A4

Supported Series: Panasonic MINAS A4 series Servo Drive.

HMI Setting:

Parameters	Recommended	Options	Notes
PLC type	Panasonic MINAS A4		
PLC I/F	RS232		
Baud rate	9600	2400 ~ 57600	
Data bits	8		
Parity	None		
Stop bits	1		
Axis no.	0 (master station only)	0 ~ F (slave)	

Device Address:

Bit/Word	Device type	Format	Range	Memo
В	Command 20	D	0 ~ 7	States (Note 3)
В	Command 27	DD	0 ~ 31	Input Signal (Note 3)
В	Command 28	DD	0 ~ 31	Output Signal (Note 3)
W	Command 01	D	0	CPU Version (Numeric
VV				format:16-bit Hex)
W	Command 05	DD	0 ~ 11	Driver Version (ASCII / 12 words)
W	Command 06	DD	0 ~ 11	Motor Version (ASCII / 12 words)
W Comn	Command 21	D	0 ~ 1	command pulse counter
	Command 21			(Numeric format: 32-bit Signed)
W Command	Command 22	D	0 ~ 1	feedback pulse counter
	Command 22			(Numeric format: 32-bit Signed)
١٨/	W Command 24	D	0	present speed
VV				(Numeric format: 16-bit Unsigned)
W Comm	Command 25	D	0	present torque
	Command 25			(Numeric format: 16-bit Unsigned)
W	Command 26	D	0 ~ 1	present deviation counter
				(Numeric format: 32-bit Signed)
W	Command 84	D	0	write parameter to EEPROM
				(Note 1)
W	Command 90	D	0	present Alarm Data



Bit/Word	Device type	Format	Range	Memo
				(Numeric format: 16-bit Unsigned)
W	Command 91	DD	1 ~ 14	Alarm History (Note 4)
VV				(Numeric format: 16-bit Unsigned)
W	Command 92	DD	1 ~ 14	Batch Alarm (Note 4)
VV				(Numeric format: 16-bit Unsigned)
W	Command 93	D	0	clear Alarm History (include
VV				EEPROM) (Note 1)
W	Command 94	D	0	Alarm Clear (Note 1)
W	Command 9B	D	0	Absolute Clear (Note 1)
W	Parameter	НН	0 ~ 7f	Individual Parameter (range: 0x00
				~ 0x7F) (Note 2)
W	Comm2D_S	D	0 ~ 1	Command 2D Signle turn data
				(Numeric format: 32-bit Signed)
W	Comm2D_M	D	0 ~ 1	Command 2D Multi-turn data
VV				(Numeric format: 32-bit Signed)

Note:

- Command 84, Command 93, Command 94, and Command 9B are write only. (These commands are able to use Set Bit Object and execute the write command after triggering Set Bit Object.). Commands other than these four are read only.
- Parameter read/write: Use device type to define address control from 00~7F.
 For example: "address_00" is mapping to "Parameter_00".
 (Please refer to Panasonic MINAS A4 Series User Manual.)
- 3. Device address type can define MINAS A4 Driver's command list.

 Command 20, Command 27, and Command 28 are Bit type, use "Operating range" to map communication order status.

For example: "Command 20_3" means "Read state_CCW". (Please refer to Panasonic MINAS A4 Series User Manual.)

4. Command 91 and Command 92 are word type, use "Operating range" to map the record of 14 alarms.

For example: "Command 91_1" means "Read alarm data_First alarm".



Wiring Diagram:

Diagram 1

RS-232 (MINAS A4 Driver CNX4 Port)

The serial port pin assignments may vary between HMI models, please click the following link for more information.

The following is the view from the soldering point of a connector.







678	MINAS A4 Driver CNX3 Port	MINAS A4 Driver CNX4 Port
$\begin{pmatrix} 3 & 4 & 5 \\ 1 & 2 & \end{pmatrix}$		3 TX
		5 RX
8P Mini-Din Male	4 GND	4 GND
MINAS A4 Driver CNX3 / CNX4 Port	7 D-	7 D-
CIVILO / CIVILA I OIL	8 D+	8 D+

RS485 cable / DVOP197	70-005	
MINAS A4 Driver		MINAS A4 Driver
8p Mini-DIN Male		8p Mini-DIN Male
7 D-		7 D-
8 D+		8 D+
4 GND		4 GND

RS232 cable / DVOP1960				
MINAS A4 Driver		MINAS A4 Driver		
9P D-SUB Female		8p Mini-DIN Male		
3 RXD		5 RXD		
2 TXD		3 TXD		
5 GND	`	4 GND		

HMI connect with one Device



HMI connect with multi devices

